

5.3 Power Adjusting

5.3.1 Power Adjusting for Remote Control

The Remote Control is mainly used to adjust the input power of the motor. When the battery is well connected and switched on, power on the Remote Control to start the pod drive, then slowly push the throttle forward position to increase the power. The maximum forward/backward power is 3KW.

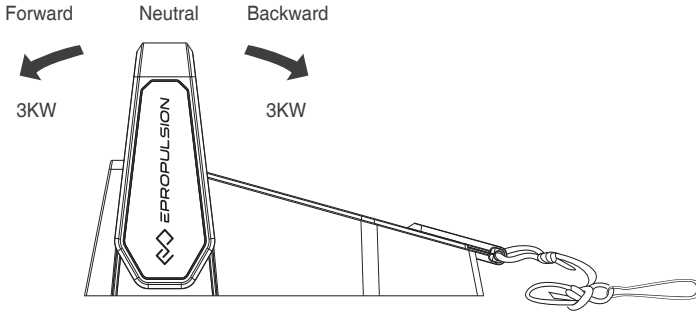


Figure 5-5

- 💡 Before power on the Remote Control, please reset the throttle to neutral position.
- 💡 If you find a blinking “**RESET**” on the display panel, you are reminded to reset the throttle to neutral position.
- 💡 If you pull the throttle from the forward position to the backward position directly, the motor will first stop shortly, then start turning to the reverse direction.